

On what depends the **robustness** of multi-source models to **missing data** in **Earth observation**?

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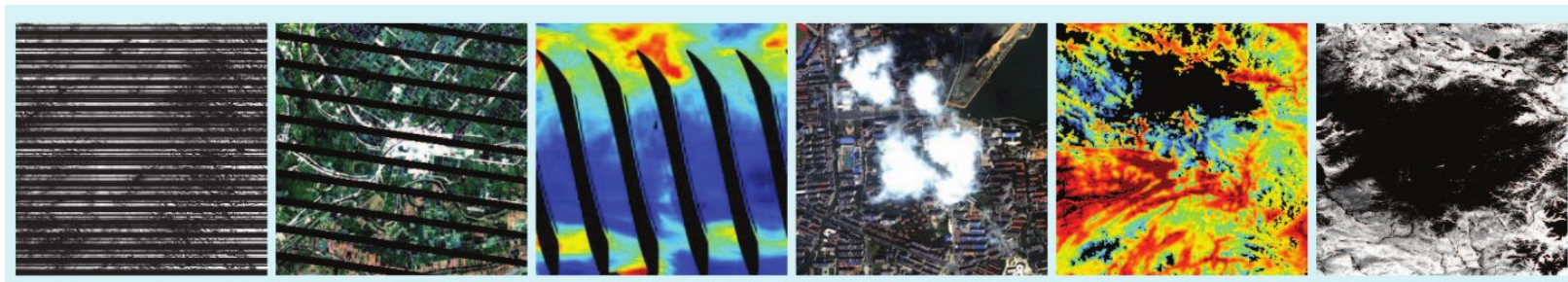
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Motivation

- The EO domain suffers from the missing data problem.
- Data collection occurs under operational constraints in real-world environment.



**Mission ends for
Copernicus
Sentinel-1B satellite**

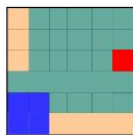
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Types of missing Earth observation data

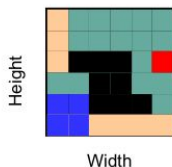


Spatial-wise missing

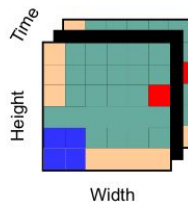
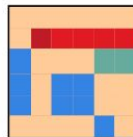
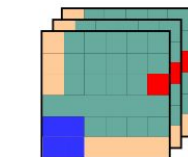
Normal



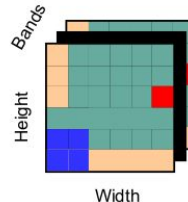
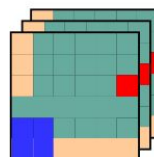
Missing case



Temporal-wise missing

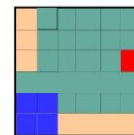


Spectral-wise missing

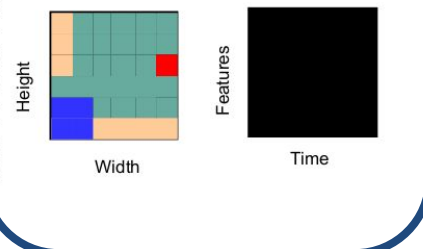


Source-wise missing

Source 1

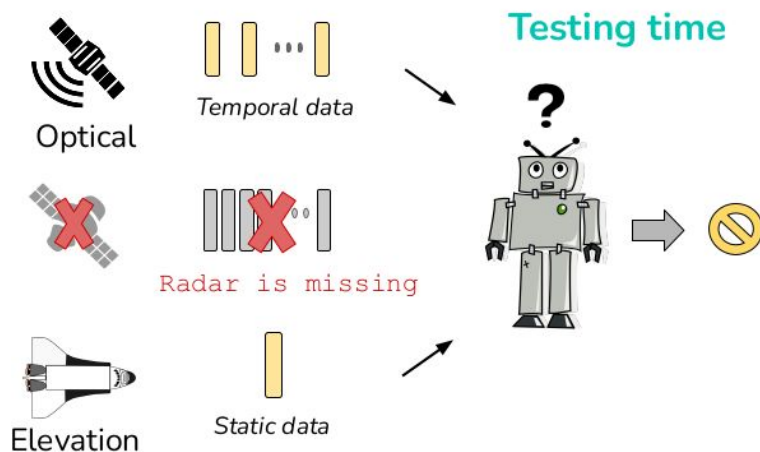


Source 2



Source-wise missing in multi-source models

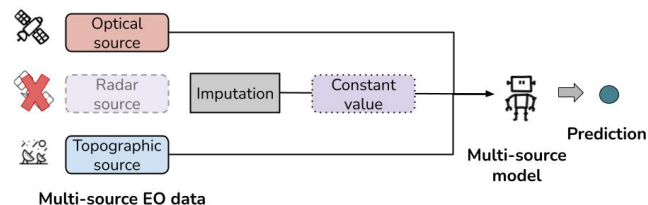
- How to handle source-wise missing data at inference time?



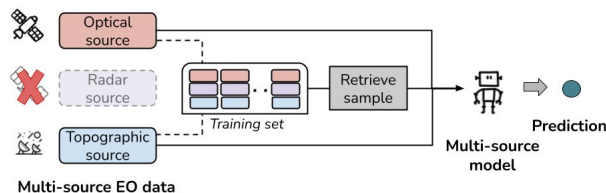
Data processing techniques

- How to handle source-wise missing data at inference time?

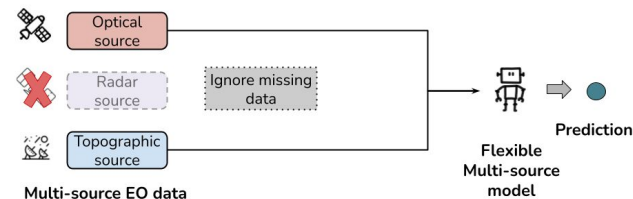
- Impute**: replace missing data with a numerical value [1].



- Retrieval**: retrieve a similar training sample based on available data [2].



- Ignore**: design a model that can ignore the missing data [3].



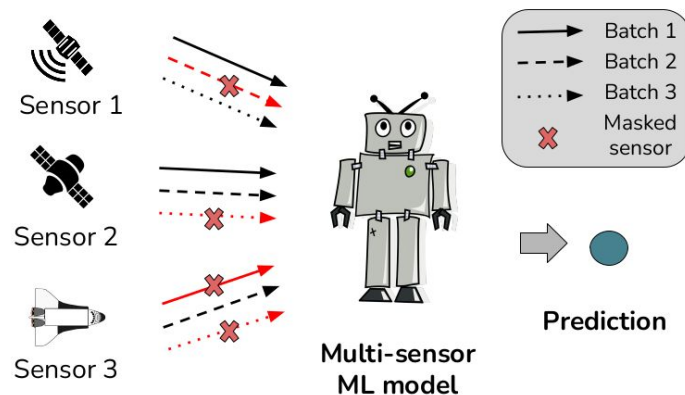
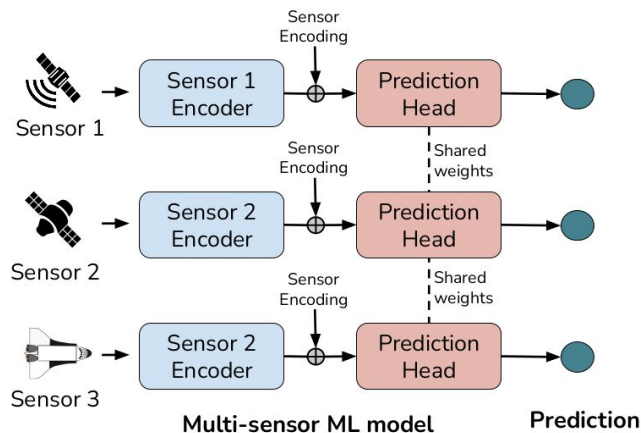
[1] Hong, Danfeng, et al. "More diverse means better: Multimodal deep learning meets remote-sensing imagery classification." *IEEE Transactions on Geoscience and Remote Sensing* (2020)

[2] Srivastava, Shivangi, et al. "Understanding urban landuse from the above and ground perspectives: A deep learning, multimodal solution." *Remote Sensing of Environment* (2019)

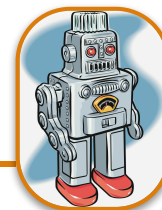
[3] Mena, Francisco, et al. "Impact assessment of missing data in model predictions for Earth observation applications." *IGARSS 2024-2024 IEEE*, 2024.

Robustness component for missing data

- How to be robust to source-wise missing data?
- **Simulate missing data** (during training)
 - e.g. sensor dropout
- **Enhance similarity** (between data sources)
 - e.g. sharing weights in per-source models



Model comparison



- Single-source model as baseline

Name	Fusion strategy	Data processing	Robustness component	Extra
ISensD [1]	Input-level	Impute (zero)	Sensor dropout	<i>concat-based fusion</i>
FSensD [2]	Feature-level	Ignore (mask)	Sensor dropout	<i>transformer-based fusion</i>
OOD-f [3]	Feature-level	Impute (zero)	Simulate all missing cases	<i>concat-based fusion</i>
TIMML [4]	Feature-level	Ignore (mask)	Sensor dropout	<i>auxiliary predictions, transformer-based fusion</i>
ESensI [1]	Ensemble-based	Ignore	Sharing weights	<i>average-based fusion</i>
Co-Ens [5]	Ensemble-based	Ignore	Prediction similarity	<i>average-based fusion</i>

[1] Mena, Francisco, et al. "Impact assessment of missing data in model predictions for Earth observation applications." IGARSS 2024-2024 IEEE, 2024.

[2] Chen, Yuxing, et al. "A novel approach to incomplete multimodal learning for remote sensing data fusion." IEEE Transactions on Geoscience and Remote Sensing (2024).

[3] Gawlikowski, Jakob, et al. "Handling unexpected inputs: incorporating source-wise out-of-distribution detection into SAR-optical data fusion for scene classification." EURASIP .1 (2023).

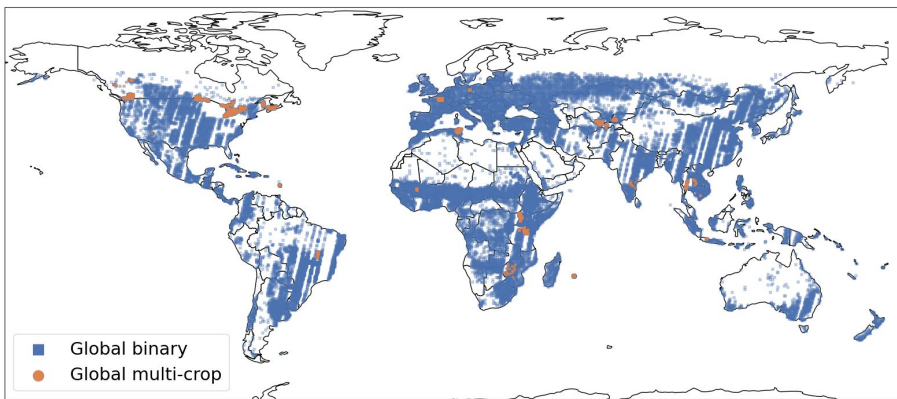
[4] Xu, Guozheng, et al. "Transformer-Based Incomplete Multi-Modal Learning for Land Cover Classification." IGARSS 2024-2024 IEEE, 2024.

[5] Xie, Yuxing, et al. "A co-learning method to utilize optical images and photogrammetric point clouds for building extraction." International Journal of Applied EO and Geoinformation 116 (2023)

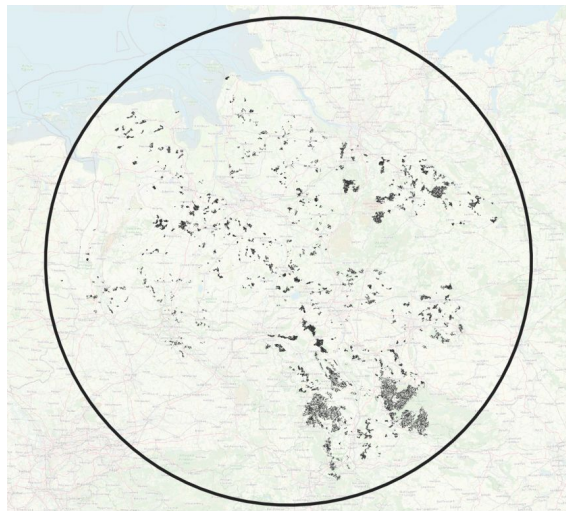
Vegetation datasets

- Datasets with temporal length over 1 year.

CropHarvest [1]: crop recognition



TreeSatAI-TS [2]:
tree-species recognition



Pixel-wise **classification** datasets



- Datasets with temporal length over 1 year.

Predictive Task	Samples	Where	When	Data sources with temporal features	Data sources with static features
Cropland classification [1]	62,100 /6,900	Global	2016-2021	optical, radar, weather	topography
Crop-type classification [1]	26,678 /2,964	Global	2016-2021	optical, radar, weather	topography
Tree-species classification [2]	38,520 /5,044	Germany	2017-2020	optical, radar	aerial image

[1] Tseng, Gabriel, et al. "Cropland: A global dataset for crop-type classification." *Thirty-fifth Conference on Neural Information Processing Systems Datasets and Benchmarks Track* (2021)

[2] Astruc, Guillaume, et al. "Omnisat: Self-supervised modality fusion for earth observation." *European Conference on Computer Vision*. Cham: Springer Nature Switzerland, 2024.

(weighted) F1 Results I

Cropland and crop-type recognition

Cropland classification

Data sources				Single	ISensD	FSensD	OOD-f	TIMML	ESensI	Co-Ens
Optical	Radar	Weather	Topography							
✓	✓	✓	✓		80.0	82.1	84.7	<u>83.1</u>	81.4	79.2
-	✓	✓	✓		72.6 (10.2)	79.0 (3.9)	82.5 (2.7)	<u>80.1</u> (3.7)	78.1 (4.2)	76.8 (3.1)
✓	-	✓	✓		79.4 (0.8)	81.8 (0.4)	84.2 (0.6)	<u>82.8</u> (0.4)	82.4 (†)	79.3 (†)
✓	✓	-	✓		<u>80.4</u> (†)	80.0 (2.6)	81.3 (4.2)	81.3 (2.2)	79.7 (2.2)	78.4 (1.0)
✓	✓	✓	-		80.0 (0.0)	82.1 (0.0)	84.2 (0.5)	<u>83.1</u> (0.0)	81.2 (0.3)	80.0 (†)
✓	-	-	-	<u>81.8</u>	80.0	79.7	79.5	80.9	<u>80.8</u>	80.9
-	✓	-	-	71.4	44.6	69.5	69.6	70.1	<u>70.7</u>	72.2
-	-	✓	-	<u>77.8</u>	60.8	75.8	<u>77.2</u>	76.2	77.3	<u>77.2</u>
-	-	-	✓	67.7	56.5	56.5	66.0	63.8	65.0	68.3
The model with the best robustness depends on the missing data scenario										
Optical	Radar	Weather	Topography							Ens
✓	✓	✓	✓		71.3	69.5	73.2	<u>72.8</u>	71.2	63.6
-	✓	✓	✓		46.1 (54.7)	60.8 (14.3)	65.2 (12.3)	<u>63.3</u> (15.0)	59.5 (19.8)	55.5 (14.6)
✓	-	✓	✓		69.8 (2.1)	68.1 (2.0)	69.9 (4.7)	71.4 (2.0)	70.2 (1.5)	60.0 (6.0)
✓	✓	-	✓		70.5 (1.1)	69.1 (0.7)	72.0 (1.7)	<u>73.0</u> (†)	73.1 (†)	66.3 (†)
✓	✓	✓	-		71.3 (0.0)	69.5 (0.0)	73.1 (0.1)	<u>72.8</u> (0.0)	71.2 (0.1)	65.5 (†)
✓	-	-	-	<u>72.8</u>	69.1	67.6	69.3	<u>71.8</u>	72.5	70.8
-	✓	-	-	<u>55.8</u>	17.4	46.9	51.6	53.7	<u>54.8</u>	56.5
-	-	✓	-		46.9	42.0	42.8	44.8	<u>45.0</u>	47.4
-	-	-	✓		28.0	<u>15.3</u>	15.1	3.1	14.8	30.0
Average					50.9	53.9	56.5	62.5	<u>59.1</u>	57.3

(weighted) F1 Results I

Tree-species recognition

$$(P_A - P_{m(s)}^*)/P_{m(s)},$$

Tree-species classification

Data sources			Single	FSensD	OOD-f	TIMML	ESensI
Optical	Radar	Aerial					
✓	✓	✓		61.8	68.0	<u>65.6</u>	62.6
-	✓	✓		59.3 (4.1)	65.3 (4.2)	<u>64.7</u> (1.4)	63.0 (†)
✓	-	✓		61.1 (1.1)	66.1 (3.0)	<u>65.2</u> (0.7)	<u>65.6</u> (†)
✓	✓	-		<u>57.5</u> (7.4)	27.1 (150.8)	59.3 (10.7)	56.4 (10.9)
✓	-	-	65.8	53.5	5.5	55.5	<u>55.3</u>
-	✓	-	55.0	51.3	10.4	52.6	<u>52.0</u>
-	-	✓	63.7	56.0	62.2	63.3	<u>62.2</u>
Average			61.5	57.2	43.5	60.9	<u>59.6</u>

VHR aerial 0.2 m



★ Sentinel-2 time series



★ Sentinel-1 time series



Differences between the best individual prediction and complementarity

Main findings



- The individual-source performance **does not necessarily** relate to their complementary effectiveness in the task.
 - Depends on the common multi-source information
- Additional data sources **are not always beneficial** in the modeling.
 - Depends on how task-informative the source is, complementarity, and model design
- A multi-source model is **not robust for all cases** of source-wise missing data.
 - Specially in single-source predictions (harder).
 - Depends on the model design.

It depends!

Analysis

Effectiveness of **model robustness** to missing data sources depends on several factors.

- A. How **task-informative** is the individual data source.
 - a. *Clue: single predictive performance*
- B. How **complementary** is the data source regarding others.
 - a. *Clue: complementarity score*
- C. How **invariant** is the model design to missing data.



Conclusion

- Robustness evaluation of various multi-source models in the literature.
- We identified **three** main factors on which robustness depends on.

Future work: Explainability and quantifying the contribution/importance of each data source.



On what depends the **robustness** of multi-source models to **missing data** in **Earth observation**?

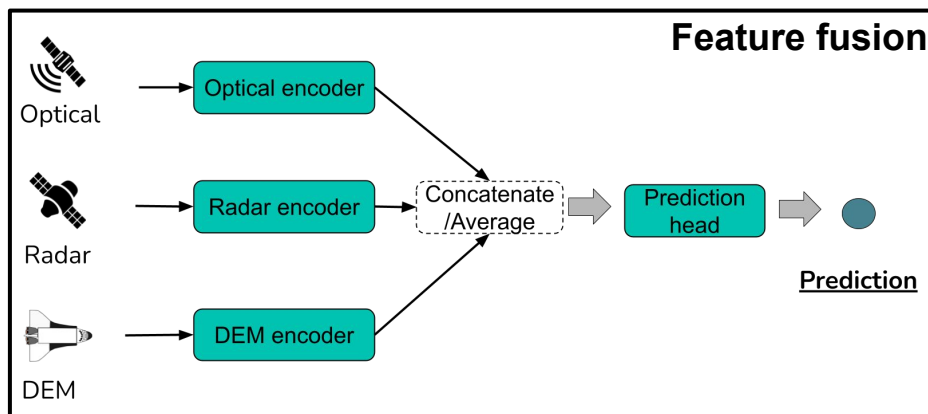
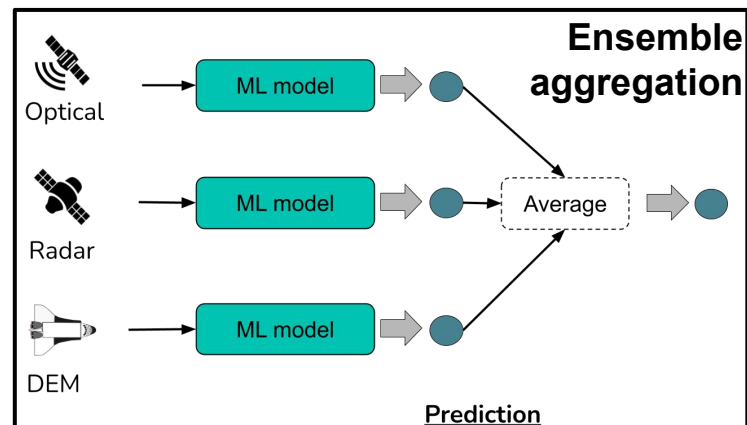
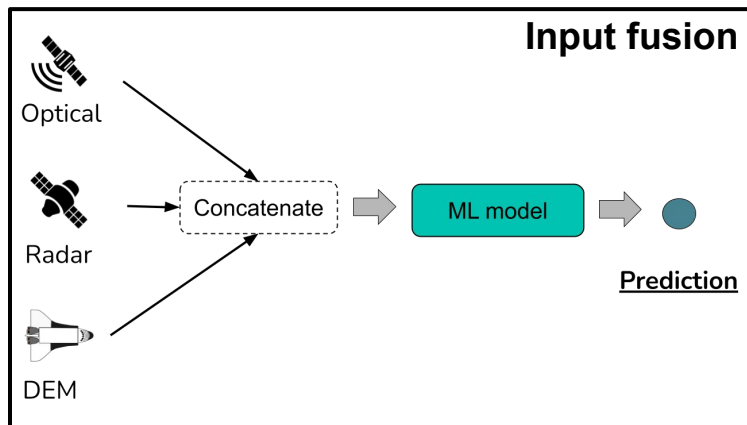
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Fusion strategies



Mena, Francisco, et al. "Common practices and taxonomy in deep multi-view fusion for remote sensing applications." *IEEE Journal of Selected Topics in Applied Earth Observations and Remote Sensing* (2024).

Model implementation

- Architecture
 - **Encoders**: Two layers with 128 units
 - Static pixel-wise sources: MLP
 - Static image sources: ResNet-50
 - Temporal views: 1D CNN
 - **Prediction Head**: a MLP with one layer of 128 units.
- Optimization:
 - ADAM
 - 128 batch size
 - early stopping
- Loss function
 - Cross entropy